# Finite form of proper orthocronous Lorentz transformations and its dynamic interpretation 

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#### Abstract

In this paper using the Pauli Algebra we obtain the finite form of a generic proper orthocronous Lorentz transformations (denoted $L_{+}^{\dagger}$ ), or in other words, we give to the exponential of a generic generator of $S L(2, \mathbb{C})$ (the universal covering group of $\mathcal{L}_{+}^{\dagger}$, the proper orthocronous Lorentz group) a closed form, which represents a generalization of the well known exponential form for pure boosts and pure rotations. We show also that there exists a dynamical interpretation of the transformations of $\mathcal{L}_{+}^{\mathrm{t}}$ when applied to the relativistic four vector velocity namely, that these transformations yield the integral solution of the equation of motion of a charged particle under the action of electric and magnetic fields in many configurations.


The developments that follow are mainly based on the well known fact that the proper orthocronous Lorentz transformations $L_{+}^{\dagger}$ can be described by the elements of $S L(2, \sigma)^{1,2}$. Each $2 \times 2$ complex matrix (an element of $a(2)$ ) can be represented by a linear combination of the base $\beta=\left\{\mathbb{1}, \sigma_{1}, \sigma_{2}, \sigma_{3}\right\}$ where $\sigma_{i}$ are the Pauli matrices. There exists an isomorphism among the four-vectors $u \in \mathbb{R}^{1,3}$ (where $\mathbb{R}^{1,3}$ is the Minkowski space) and the $2 \times 2$ matrices $U$ that are linear combinations of the base $\beta$ with real coefficients. We have:

$$
\begin{equation*}
\mathbb{R}^{1,3} \ni u \mapsto U=u^{0}+\vec{u} \equiv u^{0} \mathbb{I}+u^{i} \sigma_{i} \in \mathbb{C}(2) \tag{1}
\end{equation*}
$$

If $g$ is the Lorentz metric then $g(u, \mathrm{u})=\left(u^{0}\right)^{2}-\left(u^{i}\right)^{2}$ is represented by $g(u, \mathrm{u}) \mapsto$ $\operatorname{det} U=\left(u^{0}\right)^{2}-(\vec{u})^{2}$. We write $U \simeq u$.

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The matrices $\pm \mathrm{ME} S L(2, \mathscr{C})$ will be called for short in what follows Lorentz transformations. The action of $\mathrm{L}+$ on a four vector $\mathrm{u} \in \mathbb{R}^{1,3}$ is represented by ${ }^{3}$

$$
\begin{equation*}
U^{\prime}=M U M^{+} \tag{2}
\end{equation*}
$$

where $M^{+}$denotes the hermitian conjugated of M .
We can write the operator M as a linear combination of the basis $\beta$ with complex coefficients, i.e.:

$$
\begin{equation*}
M=w+\vec{H} \tag{3}
\end{equation*}
$$

The unimodularity condition, i.e., $\operatorname{det} \mathrm{M}=1$ is equivalent to the condition

$$
\begin{equation*}
M \widetilde{M}=\widetilde{M} M=1 \tag{4}
\end{equation*}
$$

where the operation $\sim$ called space time reversion is defined by

$$
\begin{equation*}
M=w+\vec{H} \Longrightarrow \widetilde{M}=w-\vec{H} \tag{5}
\end{equation*}
$$

A direct calculation shows that

$$
\begin{equation*}
M \widetilde{M}=w^{2}-\vec{H}^{2} \tag{6}
\end{equation*}
$$

Now, the square of a complex vector can be calculated using the Pauli product of two arbitrary vectors. We have the well known formula ${ }^{3}$

$$
\begin{equation*}
\vec{H} \vec{F}=\vec{H} \cdot \vec{F}+i \vec{H} \times \vec{F} \tag{7}
\end{equation*}
$$

where

$$
\begin{equation*}
\vec{H} \cdot \vec{F}=\frac{1}{2}(\vec{H} \vec{F}+\vec{F} \vec{H})=\sum_{i=1}^{3} H_{i} F_{i} \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
\boldsymbol{i} \boldsymbol{a} \times \vec{F}=\frac{1}{2}(\bar{H} \bar{F}-F H)=\Sigma_{i=1}^{3} i \varepsilon_{i j} H_{i} F_{j} \sigma_{k} \tag{9}
\end{equation*}
$$

From these equations we have $\boldsymbol{w}^{2}$ and $\overrightarrow{\boldsymbol{H}}^{2} \in \mathbb{C}$ and eq.(4) permit us to write

$$
\begin{equation*}
w^{2}=\cosh ^{2} z ; \quad \vec{H}^{2}=\sinh ^{2} z, \quad z \in \mathbb{C} \tag{10}
\end{equation*}
$$

We put $\boldsymbol{w}=\cosh z$ and parametrize $\overrightarrow{\mathrm{H}}$ as follows

$$
\begin{equation*}
\mathrm{H}=\widehat{F} \sinh z \tag{11}
\end{equation*}
$$

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where the complex "normalized" vector $\widehat{\mathrm{F}}\left(\widehat{F}^{2}=1\right)$ is given by

$$
\begin{equation*}
\widehat{F}=\frac{\sinh z^{+}}{|\sinh z|^{2}} \boldsymbol{H} \tag{12}
\end{equation*}
$$

In this way the operator $M$ defined by eq.(3) assumes the following form in terms of the parameters $\boldsymbol{z}$ and $\widehat{\boldsymbol{F}}$

$$
\begin{equation*}
\mathrm{M}=\cosh z+\widehat{F} \sinh z \tag{13}
\end{equation*}
$$

This is a finite form for the operator $M \in S L(2, \mathscr{C})^{3}$. This is a really convenient form since it is the finite form of the exponential of a complex vector denoted $\vec{F}$, related to the parameters $z$ and $\widehat{F}$ by

$$
\begin{equation*}
\vec{F}=z \widehat{F} \quad, \quad \vec{F}^{2}=z^{2} \quad ; \quad \widehat{F}=\frac{z^{+} \vec{F}}{|z|^{2}} \tag{14}
\end{equation*}
$$

as it can be seen at once through the series expansions ${ }^{3}$

$$
\begin{equation*}
M=\exp (\vec{F})=1+\vec{F}+\frac{\vec{F}^{2}}{2}+\frac{\vec{F}^{3}}{3!}+\cdots \tag{15}
\end{equation*}
$$

The argument of the exponential, the complex vector $\vec{F}$, defines the operator M and is said to be the generator of the transformation. $\vec{F}$ can be written as the sum of two euclidian vectors $\vec{E}, \vec{B} \in \mathbb{R}^{3}$, i.e.

$$
\begin{equation*}
\vec{F}=\vec{E}+i \vec{B} \tag{16}
\end{equation*}
$$

When' the generator $\vec{F}$ of the transformation $M$ has only a real part, i.e., $\vec{F}=\vec{E}$, the transformation is said to be a boost., In this case the operator M in eq.(13) $(z=x=|\vec{E}|, \widehat{F}=\vec{E} / E)$, is given by ${ }^{3}$

$$
\begin{equation*}
M=\cosh x+\frac{E}{|\vec{E}|} \sinh x \tag{17}
\end{equation*}
$$

Observe that the boost operators are hermitian. When the generator $\vec{F}$ of the transformation M has only an imaginary part, i.e., $\overrightarrow{\mathrm{F}}=\boldsymbol{i} \overrightarrow{\boldsymbol{B}}$, the transformation is said to be a spatial rotation. In this case the operator $M$ in eq.(13) $(z=i y=$ $i|\vec{B}|, \widehat{F}=\vec{B} / B)$ is given by

$$
\begin{equation*}
\mathrm{M}=\operatorname{cosy}+i \frac{\vec{B}}{B} \sin y \tag{18}
\end{equation*}
$$

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Observe that the rotation operators are unitary, $M^{+}=\widetilde{M}=M^{-1}$.
The solution of eq.(2) for the transformation of a relativistic four-vector $U$ under the action of a Lorentz transformation $L_{+}^{\dagger} \in \mathcal{L}_{+}^{\dagger}$ is given by ${ }^{3}$ :

Scalar part : $\quad u^{0^{\prime}}=\frac{u^{0}}{\frac{u^{0}}{|z|}\left\{|z|^{2}|\cosh z|^{2}+\left(E^{2}+B^{2}\right)|\sinh z|^{2}\right\}}$

$$
-2 \vec{u} \cdot \frac{(\vec{E} \times \vec{B})}{|z|^{2}}|\sinh z|^{2}+\frac{\vec{u} \cdot \vec{E}}{|z|^{2}} f(x, y)+\frac{\vec{u} \cdot \vec{B}}{|z|^{2}} g(x, y)(19 a)
$$

Vector part : $\quad \vec{u}^{\prime}=\frac{u^{0}}{|z|^{2}}\left\{\vec{E} f(x, y)+\vec{B} g(x, y)+2 \vec{E} \times \vec{B}|\sinh z|^{2}\right\}$

$$
\begin{align*}
& +\frac{\vec{u}}{|z|^{2}}\left\{|z|^{2}|\cosh z|^{2}-\frac{\vec{E}^{2}+\mathrm{B}^{2}}{|z|^{2}}|\sinh z|^{2}\right\}-\frac{\vec{u} \times \vec{E}}{|z|^{2}} g(x, y) \\
& +\frac{\vec{u} \times \vec{B}}{|z|^{2}} f(x, y)+\frac{2|\sinh z|^{2}}{|z|^{2}}\{(\vec{u} \cdot \vec{E}) \vec{E}+(\vec{u} \cdot \vec{B}) \vec{B}\} \tag{19b}
\end{align*}
$$

where the functions $f(\mathrm{x}, \mathrm{y})$ and $g(x, \mathrm{y})$ are defined by

$$
\begin{align*}
& f(x, y)=x \sinh 2 x+y \sin 2 y  \tag{20a}\\
& g(x, y)=y \sinh 22-x \sin 2 y \tag{20b}
\end{align*}
$$

The variables x and y are such that $z=\mathrm{x}+i y$ can be obtained from the equation $\mathrm{z}^{2}=\mathrm{F}^{2}$, by observing that $\mathrm{F}^{2}=\vec{F} \cdot \vec{F}=\vec{E}^{2}-\mathrm{B}^{2}+2 i \vec{E} \cdot \mathrm{~B}$. We get:

$$
\begin{align*}
x^{2} & =\frac{1}{2}\left\{|z|^{2}+\left(\vec{E}^{2}-\vec{B}^{2}\right)\right\}  \tag{21a}\\
y^{2} & =\frac{1}{2}\left\{|z|^{2}-\left(\vec{E}^{2}-\vec{B}^{2}\right)\right\} \tag{21b}
\end{align*}
$$

and also

$$
\begin{equation*}
|z|^{2}=\sqrt{\left(\vec{E}^{2}-\vec{B}^{2}\right)^{2}+4(\vec{E} \cdot \vec{B})^{2}} \tag{21c}
\end{equation*}
$$

Eqs(19a) and (19b) reduce to well known formulas in the cases $\vec{E}=0$ (rotation) and $\vec{B}=0$ (pure boost) ${ }^{3}$.

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The result we want to show now is that a transformation of $\mathcal{L}_{+}^{\dagger}$ conveniently parametrized gives the integral solution for the motion of a charged particle under the action of an electric and magnetic field. This result is due to the fact that the electromagnetic field (which as well known, is represented by a two-form) is represented by objects of the same mathematical nature as the generators of $S L(2, \mathbb{C})$. . The electric field can be written as a linear combination of boost gen- $_{\text {g }}$ erators, whereas the magnetic field can be written as a linear combination of the rotation generators, which makes this representation of the fields significative ${ }^{\mathrm{g}}$, since we know that a charged particle in the presence of a constant electric field suffers an acceleration in the direction of the field, and in the presence of a constant magnetic field the charged particle suffers a rotation ${ }^{3,5}$. In resume, in the Pauli algebra which is isomorphic to $\mathbb{C ( 2 ) ^ { 3 , 9 , 1 0 }}$ the electromagnetic field is represented by a complex vector analogous to the one given by eq.(16). ${ }^{3}$

We must comment here that the result quoted above has already been discussed in the literature ${ }^{4,5}$ using the space-time algebra $\mathbb{R}_{1,3}$. However due to the lack of the formula for a general Lorentz transformation (eq.(13)) in ${ }^{4,5}$ the authors work with the generic Lorentz transformation written as a product of a boost and a rotation. The final formulas obtained in ${ }^{4}$ eqs. (2.25), (2.26), (2.27) are equivalent to our eqs.(19). The results obtained in ${ }^{5}$ are only an approximation obtained with the Cambell-Baker-Hausdorff formula.

We now show the validity of the above statement. We start by writing the generator of the Lorentz transformation as

$$
\begin{equation*}
\vec{f}=\frac{\alpha}{2} \vec{F}_{\tau} \tag{22}
\end{equation*}
$$

where $\vec{F}=\vec{E}+i \vec{B}$ is the electromagnetic field, o! $E \mathrm{R}$ is a constant and $\tau$ is an appropriate real parameter. We denote by $M(\tau)$ the transformation generated by

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$\vec{f}$ and rewrite eq.(2) as

$$
\begin{equation*}
U(\tau)=M(\tau) U M^{+}(\tau) \tag{23}
\end{equation*}
$$

where $U(\tau)=\left(\mathrm{u}^{0}(\mathrm{r}), \vec{u}(\tau)\right)$ and $\boldsymbol{U}=\left(\mathrm{u}^{0}, \vec{u}\right)$.
Observe that in eq.(23) the initial four-vector $U$ does not depend on the parameter $\boldsymbol{T}$.

By differentiating both msmbers of eq.(23) in relation to $r$ we have

$$
\begin{equation*}
\frac{d U}{d \tau}=\frac{\alpha}{2}\left(\vec{F} U(r)+U(\tau) \vec{F}^{+}\right) \tag{24}
\end{equation*}
$$

Now, from the Pauli product of two vectors (eq.(7)), taking into account that $\vec{F}^{+}=\vec{E}-i \vec{B}$, it follows that the right hand side of eq.(24) is the Lorentz force, i.e.

$$
\begin{equation*}
\frac{1}{2}\left(\vec{F} U+U \vec{F}^{\dagger}\right)=u^{0} \vec{E}+\vec{u} \cdot \vec{E}+\vec{u} \times \vec{B} \tag{25}
\end{equation*}
$$

We can then write the scalar and vector parts of eq.(24) as:

$$
\begin{equation*}
\frac{d u^{0}}{d \tau}=\alpha \vec{u} \cdot \vec{E}, \frac{d}{d \tau} \vec{u}=\alpha\left(u^{0} \vec{E}+\vec{u} \times \vec{B}\right) \tag{26}
\end{equation*}
$$

From eq.(26) we see that $\alpha=q / m c$, where q is the charge of the particle, m its mass, c is the velocity of light and $\tau$ must be identified with the proper time parameter along the world line of the charged particle. With these identifications, the velocity four- vector $U$ given by eq.(23) is indeed the integral solution of eq.(26) for constant electric and magnetic fields.

In eq.(23) $U$ is interpreted, of course, as the initial four-vector velocity since for $\mathrm{r}=0$ it is $M(0)=\mathbb{1}$ and $U(0)=U$.

We mention that there are another simple problems that can be solved with the above technique. These are the cases where there exists only the electric field or only the magnetic field and in both cases the fields have a constant direction varying only their intensity and in a convenient way such that from Maxwell's equations no other fields arise. In these cases the solution of the motions equations (eq.(23)) are given by transformations $\mathrm{M} \in S L(2, \mathscr{C})$ in which the generator has the form $\vec{f}=\int d \tau z(\tau) \widehat{F}$ and the electric or rnagnetic field is given by $\vec{F}=z(\tau) \widehat{F}$.

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We emphasize also that the above technique can be extended to deal with the general problem of motion of a charged particle in presence of an arbitrary electromagnetic field, i.e., the solution of the motion's equations still can be written as a Lorentz transformation as in eq.(23). We must only change the generator of the Lorentz transformation (eq.(22)) conveniently ${ }^{13,14}$. With this new technique we will study some approximations ${ }^{14}$ that can be useful in some practice applications.

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## Resumo

Neste trabalho usando-se a álgebra de Pauli obtemos a forma finita de uma transformação de Lorentz própria e ortócrona genérica (denotada $L^{\dagger}+$ ), ou em outras palavras, damos à exponencial de um gerador genérico do $\mathrm{SL}(2, \mathrm{C})$ (o grupo de recobrimento universal de $\hat{f}_{+}^{\dagger}$, o grupo de Lorentz próprio e ortócrono) uma forma fechada, que representa uma generalização das formas exponenciais bem conhecidas para boosts e rotações puras. Mostramos também que existe uma interpretação dinâmica das transformações de $\mathcal{L}_{+}^{\uparrow}$ quando aplicadas ao quadrivetor velocidade relativista, i.e., que estas transformações fornecem a solução integral da equação de movimento de uma partícula carregada sob a ação de campos elétrico e magnético em muitas configurações.


[^0]:    * The proof of this result involves knowledge of the structure of the Clifford algebra $\mathbb{R}_{1,3}$ and the fact that $\operatorname{Spin}_{+}(1,3) \simeq S L(2, \widetilde{C})$ C $\mathbb{R}_{1.3}^{+} \simeq P \simeq \mathbb{C}(2)(P$ is the Pauli-algebra and $\mathbb{R}_{1,3}^{+}$is the even subalgebra of $\mathbb{R}_{1,3}$ ). For more details see references ${ }^{6,7,8,9,10,11,12}$.

