

## Riemannian approach for gravitational Yang-Mills equations in the macroscopic case

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**Abstract** A Yang-Mills approach for gravitation is considered here. It shows two dynamical equations, one for curvature and other for torsion. In the Riemannian limit Einstein's equation is obtained.

### 1. Introduction

An argument to consider a Yang-Mills (YM) classical approach for gravitation is its geometrical analogy with general relativity (GR). If we look for a space-time gauge model for gravitation, it is necessary to investigate the features of space-time gauge-like characteristics. On any differentiable manifold there is the bundle of affine frames, naturally defined, whose structural group is the affine linear group  $AL(n, R) = GL(n, R) \times T_n$ . For the space-time case, in particular, the requirement of Lorentz frames reduces  $AL(n, R)$  to the Poincaré group  $P = \mathcal{L} \times T_4$ .

However, there is a lot of criticism concerning a YM gravitational model for the Poincaré group. The main point frequently made is that GR does not have the entire Poincaré local symmetry of space-time. Gauge theories for the Poincaré and de Sitter groups have been extensively studied as alternative theories for gravitation'.

In a previous paper<sup>2</sup> we have shown a YM gravitational model for the Poincaré group, under a Inonu-Wigner contraction of the gauge fields. The absence of metric, because  $P$  is not a semi simple group, does not allow one to establish a lagrangian for the theory. Such a problem has been circumvented by means of Lie

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algebra invariants. This approach turns out to be a de Sitter theory, supplemented by weak constraints.

Stelle and West<sup>3</sup> analysed in detail the local geometrical structure of GR, as a gauge theory for the de Sitter group  $SO(3, 2)$ . To reproduce the structure of Einstein-Cartan theory, the  $SO(3, 2)$  gauge **symmetry** was spontaneously broken down to the Lorentz group. In this approach the gravitational vierbein **and** spin connections were derived from the original  $SO(3, 2)$  gauge fields, by passing over to a set of non-linearly-transforming fields, through a redefinition involving a Goldstone field. The original  $SO(3, 2)$  gauge fields generated **pseudo-translations** and rotations in the so-called **internal** anti-de Sitter space, under a kind of parallel transport.

Norris et al.<sup>4</sup> proposed an underlying fibre-bundle **structure** for gauge theories of gravitation, and an extension to an affine structure group. They considered an extension of the linear frame bundle to the **affine** frame bundle, and pointed out that the torsion is just one part of the "**total curvature**" (curvature **+** torsion).

Mielke<sup>5</sup>, within the framework of differential **geometry**, considered a Yang's parallel displacement gauge theory with respect to pure gravitational fields. He showed that, in a four-dimensional Riemannian manifold, double self-dual solutions obey Einstein's vacuum equation with a cosmological term, **whereas** the double anti-self dual configurations satisfy the Raynitch conditions of geometrodynamics. Under duality conditions the Stephenson-Kilmister-Yang theory not only embraces  $R_{\mu\nu} = 0$ , but Nordstrom's vacuum theory as well.

The lagrangian structure of Poincaré gauge field equations for gravitation, and their Einsteinian content, under duality conditions for the sourceless case, is already known<sup>6</sup>.

The disagreements to a Poincaré gauge model for gravitational may be justified by two main reasons: it is not a lagrangian theory under gauge-like conditions and if one tries to quantize it, vertices are not well defined<sup>7</sup>. The principal argument to discard GR, as a candidate to a gauge model, is because it **is** not renormalizable. An amended theory, like the de Sitter theory, which **is** renormalizable in the sourceless case, becomes divergent if one considers the stress-energy  $T_{\mu\nu}$  as a

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source. Moreover,  $T_{\mu\nu}$  cannot be a source for a microscopic case, because it is a macroscopic quantity (it describes a distribution of mass-energy).

In this paper our objective is to deal with YM equations, for the Poincaré group, and show how Einstein's equation can be derived by considering a macroscopic case.

**2. Field equations**

Poincaré Lie algebra is a vector space, and it is the direct sum of the Lorentz and translation sectors. In a basis with generators  $\{J_{ab}, I_c\}$ , an affine connection  $\bar{\Gamma}$  on the P bundle decomposes into

$$\bar{\Gamma} = \Gamma + S \tag{2.1}$$

where  $\Gamma = J_a^b \Gamma_{b\mu}^a dx^\mu$  is a Lorentz connection form and  $S = I_c h_\lambda^c dx^\lambda$  is the solder form<sup>8</sup>.

Such a decomposition affects the curvature of  $\bar{\Gamma}$

$$\bar{F} = F + T \tag{2.2}$$

where F and T are the curvature and torsion of  $\bar{\Gamma}$

$$F = d\Gamma + \Gamma \wedge \Gamma \tag{2.3}$$

$$T = dS + \Gamma \wedge S + S \wedge \Gamma \tag{2.4}$$

The above decomposition of the Lie algebra gives rise to Bianchi identities

$$dF + [\Gamma, F] = 0 \tag{2.5}$$

$$dT + [\Gamma, T] + [S, F] = 0 \tag{2.6}$$

Yang-Mills equations can be written, by duality symmetry, for any group, once its structure constants are known. For the P group they are

$$d * F + [\Gamma, *F] = 0 \tag{2.7}$$

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$$d * T + [\Gamma, *T] + [S, *F] = 0 \quad (2.8)$$

stating field equations for the sourceless case. Sources may be inserted in the above equations, by considering a break of such a symmetry. These sources should be the Noether current densities, whose charges are the generators of the  $P$  group. Therefore, at a first sight, they could be the density of relativistic angular momentum  $M$  and the stress-energy  $\theta$  :

$$d * F + [\Gamma, *F] = *M \quad (2.9)$$

$$d * T + [\Gamma, *T] + [S, *F] = *\theta \quad (2.10)$$

One notices that torsion is always present in the bundle of frames, and its vanishing must lead to general relativity.

### 3. Riemannian limit

The above equations may be projected onto the base-manifold, Minkowski space-time, of the  $P$ -bundle, by means of the four-legs  $h^a_\alpha$ . Locally this base-manifold is endowed with a Riemannian structure, if we consider a Levi-Civita connection:

$$d * F + [\Gamma, *F] = *M \quad (3.1)$$

$$[S, *F] = *\theta \quad (3.2)$$

which means in components

$$\partial^\lambda \tilde{F}^a_{b\mu\lambda} + \Gamma^{a\lambda}_c \tilde{F}^c_{b\mu\lambda} - \Gamma^{c\lambda}_b \tilde{F}^a_{c\mu\lambda} = M^a_{b\mu} \quad (3.3)$$

$$S^b_\lambda \tilde{F}^{a\cdot\lambda}_{b\cdot\mu} = \theta^a_\mu \quad (3.4)$$

where  $\tilde{F}$  is the dual of  $F$ .

In the dual basis<sup>8</sup> these equations become, in Riemann space-time,

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$$\nabla^\lambda \tilde{R}^\alpha_{\beta\mu\lambda} = M^\alpha_{\beta\mu} \quad (3.5)$$

$$\tilde{R}^\alpha_{\beta\cdot\mu} = \theta^\alpha_\mu \quad (3.6)$$

where  $\tilde{R}$  is the dual Riemann tensor, whose components are

$$\tilde{R}^{\alpha\beta\lambda\sigma} = \frac{1}{4} \epsilon^{\alpha\beta\gamma\delta} R_{\gamma\delta\tau\rho} \epsilon^{\tau\rho\lambda\sigma} \quad (3.7)$$

By lowering and raising suffixes, we may write

$$\tilde{R}^{\alpha\beta}_{\lambda\sigma} = -\frac{1}{4} \epsilon^{\alpha\beta\gamma\delta} R^{\tau\rho}_{\gamma\delta} \epsilon_{\lambda\sigma\tau\rho} \quad (3.8)$$

and contracting with  $a = \lambda$  we get

$$\tilde{R}^{\alpha\beta}_{\sigma\sigma} = \frac{1}{4} \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\alpha\sigma\tau\rho} R^{\tau\rho}_{\gamma\delta} \quad (3.9)$$

Using the property

$$\epsilon^{\alpha\beta\gamma\delta} \epsilon_{\alpha\sigma\tau\rho} = 2(\delta^\beta_\sigma \delta^\gamma_\tau \delta^\delta_\rho + \delta^\beta_\tau \delta^\gamma_\rho \delta^\delta_\sigma + \delta^\beta_\rho \delta^\gamma_\sigma \delta^\delta_\tau) \quad (3.10)$$

we are led to

$$\tilde{R}^{\alpha\beta}_{\alpha\sigma} = -\frac{1}{2} \delta^\beta_\sigma R + R^\beta_\sigma = G^\beta_\sigma \quad (3.11)$$

which are the components of Einstein tensor.

So, eq.(3.5), by contraction ( $\alpha = \mu$ ), leads to

$$\nabla^\lambda G_{\beta\lambda} = M_\beta \quad (3.12)$$

which violates the conservation law  $\nabla^\lambda G_{\beta\lambda} = 0$ . We conclude that M cannot be inserted in eq.(2.9) as a source. However, if we take  $\theta^\alpha_\mu = kT^\alpha_\mu$  (k being a constant) eq. (3.6) becomes Einstein's equation

$$R^\alpha_\mu - \frac{1}{2} \delta^\alpha_\mu R = -kT^\alpha_\mu \quad (3.13)$$

#### 4. Conclusion

The scenario developed here points out that Einstein's equations emerge from a break of dual symmetry of **Bianchi's** identity for torsion. Such a break cannot be taken for curvature, otherwise the conservation of **Einstein's** tensor will not be satisfied. Moreover, this approach yields a dynamical equation of the torsion field, for a general connection.

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#### References

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8. In reality  $\Gamma$  can be defined in many different ways, with  $S$  being a horizontal form **too**, of a more general type. The **solder** form is particularly convenient

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because, when written in a frame given by the four-leg field  $h_{\alpha}^a$ , its components are those of the dual basis. See, for example, S. **Kobayashi** and K. Nomizu, Foundations of *Differential* Geometry, Interscience, N.Y. vol. I (1963).

**Resumo**

Considera-se aqui um modelo de Yang-Mills para a gravitação. Este apresenta duas equações dinâmicas, **uma** para a curvatura e outra para a torção. No limite Riemanniano as equações de **Einstein são** obtidas.