

Propagator for a Charged Particle in Time-Dependent Electromagnetic Field and Quadratic Potential

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Abstract Through a time-dependent linear transformation and the time substitution, we can evaluate exactly the propagator for a charged particle in a time-dependent electromagnetic field subjected to a time-dependent quadratic potential.

1. INTRODUCTION

It is well known that for a quadratic Lagrangian, the propagator is related to the classical action through the Van Uleck-Pauli formula^{1,2}. However, the evaluation of the classical action is not always simple. The time-dependent linear coordinate transformations with new-time have been used by Junker and Inomata³, and by Cheng⁴ to transform the original quadratic action into a new quadratic action whose classical action can be evaluated exactly. Later several authors^{5,6} derived such transformations in a broader sense by applying a non-linear superposition law of Ray and Reid⁷. In this paper we are able to deduce them from a Feynman path integral by considering the mid-point expansion⁸⁻¹⁰ for each short-time action, and to obtain the propagator for a time-dependent harmonically bound charged particle in a time-dependent electromagnetic field.

For a time-dependent harmonically bound charged particle of charge q and mass m subject to a time-dependent electromagnetic field $\vec{E}(t)$ and $\vec{B}(t)$ (along the z direction), the Lagrangian has the form

$$L(\vec{r}, \dot{\vec{r}}, t) = L_{||}(z, \dot{z}, t) + L_{\perp}(\vec{r}_{\perp}, \dot{\vec{r}}_{\perp}, t) \quad (1)$$

with

$$L_{||}(z, \dot{z}, t) = \frac{m}{2} [\dot{z}^2 - \omega_z^2(t) z^2] + qE_{||}(t)z \quad (2)$$

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$$L_1(\vec{r}_1, \dot{\vec{r}}_1, t) = \frac{m}{2} \{\dot{\vec{r}}_1^2 - [\omega_x^2(t)x^2 + \omega_y^2(t)y^2] + \omega(t)(x\dot{y} - y\dot{x})\} + q\vec{E}_1 \cdot \vec{r}_1 \quad (3)$$

where $\omega(t) = qB(t)/mc$ is the cyclotron frequency, \vec{r}_1 and $\dot{\vec{r}}_1(t)$ denote the components of \vec{r} and $\dot{\vec{r}}(t)$ perpendicular to $\vec{B}(t)$. Here $\omega_x(t)$, $\omega_y(t)$ and $\omega_z(t)$ are, respectively, the oscillator frequencies along x , y and z directions. Since the z coordinate is separated from the \vec{r} , (x and y) coordinates in eq. (1), the propagator is of the form

$$K(\vec{r}'', t''; \vec{r}', t') = K_{11}(z'', t''; z', t') K_1(\vec{r}_1'', t''; \vec{r}_1', t') \quad (4)$$

with

$$\begin{aligned} K_{11}(z'', t''; z', t') = & (m/2\pi i \hbar f(t'))^{1/2} \exp\{-im/2\hbar f(t'') [z'^2 \dot{f}(t') + 2z'z'' \\ & - z''^2 \dot{g}(t'')] \} \exp\{(i/\hbar f(t'')) [z' \int_{t'}^{t''} E_{11}(t) f(t) dt + z'' \int_{t'}^{t''} E_{11}(t) g(t) dt \\ & - (1/m) \int_{t'}^{t''} \int_{t'}^t E_{11}(t) f(t) E_{11}(\theta) g(\theta) dt d\theta] \} \end{aligned} \quad (5)$$

being the propagator¹¹ of a time-dependent harmonic oscillator. In eq.(5) the functions $f(t)$ and $g(t)$ satisfy the following differential equations

$$\ddot{f}(t) + \omega_z^2(t)f(t) = 0 \quad f(t'') = 0 \quad \text{and} \quad \dot{f}(t'') \approx -1 \quad (6)$$

$$\ddot{g}(t) + \omega_z^2(t)g(t) = 0 \quad g(t') = 0 \quad \text{and} \quad \dot{g}(t') \approx 1 \quad (7)$$

Now we are only left to evaluate the propagator of the Lagrangian (3), which will be carried out by using time-dependent linear coordinate transformation with new-time for a special case.

2. SPACE TRANSFORMATION AND TIME SUBSTITUTION

For the Lagrangian (3), the propagator can be expressed as the path integral

$$K_1(\vec{r}_1'', t''; \vec{r}_1', t') = \int \dots \int \exp\{i/\hbar \int_{t'}^{t''} L_1(\vec{r}_1, \dot{\vec{r}}_1, t) dt\} D\vec{x}(t) D\vec{y}(t) \quad (8)$$

where $Dx(t)Dy(t)$ is the usual two-dimensional Feynman differential measure. Using Feynman's polygonal paths, the propagator (8) becomes

$$K_1(\vec{r}_1', t'; \vec{r}_1, t) = \lim_{\epsilon_j \rightarrow 0} \left(\frac{m}{2\pi i \hbar \epsilon_j} \right)^N \int \dots \int \exp \left\{ \frac{i}{\hbar} \sum_{j=1}^N S(\vec{r}_j, \vec{r}_{j-1}; \epsilon_j) \right\} \prod_{j=1}^{N-1} dx_j dy_j \quad (9)$$

with

$$S(\vec{r}_j, \vec{r}_{j-1}; \epsilon_j) = (m/2\epsilon_j) \{ (x_j - x_{j-1})^2 + (y_j - y_{j-1})^2 + (\epsilon_j \omega_j / 2) [(x_j + x_{j-1})(y_j - y_{j-1}) - (y_j + y_{j-1})(x_j - x_{j-1})] - \epsilon_j^2 (\omega_j^2 x_j^2 + \omega_j^2 y_j^2) \} + q\epsilon_j (E_{xj} x_j + E_{yj} y_j) \quad (10)$$

For later convenience we set $\epsilon_j = t_j - t_{j-1}$ and $F_j = F(t_j)$ and $\bar{F}_j = F(\bar{t}_j)$ ($\bar{t}_j = (t_j + t_{j-1})/2$) for any function $F(t)$.

Introducing the time-dependent linear transformations of space

$$x(t) = s_x(t)X(\tau) \quad , \quad y(t) = s_y(t)Y(\tau) \quad (11)$$

and the time substitution

$$d\tau = u(t)dt \quad , \quad (12)$$

we obtain the following relations¹⁰

$$x_j - x_{j-1} = s_{xj} \Delta X_j + \epsilon_j \bar{s}_{xj} \bar{X}_j \quad , \quad y_j - y_{j-1} = s_{yj} \Delta Y_j + \epsilon_j \bar{s}_{yj} \bar{Y}_j \quad , \quad (13)$$

by expanding eq.(11) about the mid-point \bar{t}_j in the time interval $[t_{j-1}, t_j]$ to terms of order ϵ_j . Here we have let $\Delta X_j = X(\tau_j) - X(\tau_{j-1})$, $\bar{X}_j = (X(\tau_j) + X(\tau_{j-1}))/2$ and similar for ΔY_j and \bar{Y}_j . Substituting eq.(13) into eq.(10), we have

$$\begin{aligned} S(\vec{r}_j, \vec{r}_{j-1}; \epsilon_j) = & \Delta G_{j,j-1} + (m/2\epsilon_j) \{ s_{xj}^2 (\Delta X_j)^2 + s_{yj}^2 (\Delta Y_j)^2 \\ & + \epsilon_j \bar{s}_{xj} \bar{s}_{yj} \bar{s}_{yj} (\bar{X}_j \Delta Y_j - \bar{Y}_j \Delta X_j) + \epsilon_j \bar{\omega}_j \bar{X}_j \bar{Y}_j (\bar{s}_{xj} \dot{\bar{s}}_{yj} - \dot{\bar{s}}_{xj} \bar{s}_{yj}) - \epsilon_j^2 [\bar{s}_{xj} \ddot{\bar{s}}_{xj} \\ & + \omega_{xj}^2 \bar{s}_{xj} \bar{X}_j^2 + \bar{s}_{yj} (\ddot{\bar{s}}_{yj} + \omega_{yj}^2 \bar{s}_{yj}) \bar{Y}_j^2] \} + q\epsilon_j (\bar{s}_{xj} \bar{E}_{xj} \bar{X}_j + \bar{s}_{yj} \bar{E}_{yj} \bar{Y}_j) \end{aligned} \quad (14)$$

with

$$\Delta G_{j,j-1} = \left\{ \left[\frac{\dot{\bar{s}}_{xj} x_j^2}{2\bar{s}_{xj}} + \frac{\dot{\bar{s}}_{yj} y_j^2}{2\bar{s}_{yj}} \right] - \left[\frac{\dot{\bar{s}}_{xj-1} x_{j-1}^2}{2\bar{s}_{xj-1}} + \frac{\dot{\bar{s}}_{yj-1} y_{j-1}^2}{2\bar{s}_{yj-1}} \right] \right\} \quad (15)$$

after simplifications.

In order to get rid of the $\bar{X}_j \bar{Y}_j$ term in eq. (14), we must let

$$\bar{s}_{xj} \dot{\bar{s}}_{yj} - \dot{\bar{s}}_{xj} \bar{s}_{yj} = 0 \quad . \quad (16)$$

We now choose

$$\bar{s}_{xj} + \omega_{xj}^2 \bar{s}_{xj} = 0 \quad \text{and} \quad \bar{s}_{yj} + \omega_{yj}^2 \bar{s}_{yj} = 0 \quad . \quad (17)$$

In order to satisfy both eq. (16) and eq. (17), we have to consider the following special case hereafter:

$$\bar{s}_j = \bar{s}_{xj} = \bar{s}_{yj} \quad , \quad \Omega_j^2 = \omega_{xj}^2 = \omega_{yj}^2 \quad (18)$$

Using the time substitution eq. (12) or $\sigma_j = \tau_j - \tau_{j-1} = \bar{u}_j E_j$, we obtain from eqs. (14) and (17)

$$\begin{aligned} S(\vec{r}_j, \vec{r}_{j-1}; \sigma_j) = & \Delta G_{j,j-1} + (m \bar{u}_j \bar{s}_j^2 / 2 \sigma_j) \{ (\Delta X_j)^2 + (\Delta Y_j)^2 + \sigma_j \bar{u}_j (\bar{X}_j \Delta Y_j \\ & - \bar{Y}_j \Delta X_j) / \bar{u}_j \} + q \bar{s}_j \sigma_j (\bar{E}_{xj} \bar{X}_j + \bar{E}_{yj} \bar{Y}_j) / \bar{u}_j \quad . \end{aligned} \quad (19)$$

Choosing

$$\bar{s}_j^2 \bar{u}_j = 1 \quad , \quad \bar{s}_j^2 \bar{\omega}_j = \omega_0 \quad (20)$$

with ω_0 being a constant, eq. (19) becomes

$$\begin{aligned} S(\vec{r}_j, \vec{r}_{j-1}; \sigma_j) = & \Delta G_{j,j-1} + (m/2 \sigma_j) \{ (\Delta X_j)^2 + (\Delta Y_j)^2 + \sigma_j \omega_0 (\bar{X}_j \Delta Y_j - \bar{Y}_j \Delta X_j) \} \\ & + q \bar{s}_j^3 \sigma_j (\bar{E}_{xj} \bar{X}_j + \bar{E}_{yj} \bar{Y}_j) \quad . \end{aligned} \quad (21)$$

Using eqs. (11), (12) and (18), the Feynman path differential measure is given

$$(m/2\pi i \hbar \epsilon_j)^N \prod_{j=1}^{N-1} dx_j dy_j = (s' s'')^{-1} (m/2\pi i \hbar \sigma_j)^N \prod_{j=1}^{N-1} dX_j dY_j \quad (22)$$

by symmetrizing about the end points in the time interval $[t_{j-1}, t_j]$. Combining eq. (19) with eq. (22), we obtain our principal result

$$K_{\perp}(\vec{r}_1'', t''; \vec{r}_1', t') = (s' s'')^{-1} G_{\mathcal{S}}(\vec{r}_1'', \vec{r}_1') K(\vec{R}_1'', \tau''; \vec{R}_1', \tau') \quad (\vec{R}_1 = (X, Y)) \quad (23)$$

with

$$G_{\mathcal{S}}(\vec{r}_1'', \vec{r}_1') = \exp\{-(im/2\hbar) [(\dot{s}''/s'')(x''^2 + y''^2) - (\dot{s}'/s')(x'^2 + y'^2)]\} \quad (24)$$

where $K(\vec{R}_1'', \tau''; \vec{R}_1', \tau')$ is the propagator of a charged particle in a constant magnetic field with the cyclotron frequency ω_0 and in a time-dependent electric field $\vec{\epsilon}(\tau) = \vec{E}(t(\tau))s^3(t(\tau))$, which has been evaluated by us¹³.

Without loss of generality we now consider the case of $E_x(t)=0$ or $\epsilon(\tau) = E_y(\tau)$ hereafter. We then have¹³ ($T = \tau'' - \tau'$)

$$K(\vec{R}_1'', \tau''; \vec{R}_1', \tau') = (m/2\pi i \hbar T) (\omega_0 T/2 \sin(\omega_0 T/2)) \times \exp\{(im\omega_0/2\hbar) [\cot(\omega_0 T/2)/2] [(X''-X')^2 + (Y''-Y')^2] + (X'Y''-X''Y')\} \quad (25)$$

$$\times \exp\{(iq/\hbar \sin(\omega_0 T)) [(Y''\epsilon_b + Y'\epsilon_a) - (q/m\omega_0)\epsilon_0]\} \times \exp\{(iqm\omega_0/4\hbar \tan(\omega_0 T/2)) \epsilon_{ab} (q\epsilon_{ab} - 2[(X'-X'')H + (Y'+Y'')\tan(\omega_0 T/2)])\}$$

with

$$\epsilon_a = \int_{\tau'}^{\tau''} \epsilon_y(\tau) \sin[\omega_0(\tau''-\tau)] d\tau, \quad \epsilon_b = \int_{\tau'}^{\tau''} \epsilon_y(\tau) \sin[\omega_0(\tau-\tau')] d\tau \\ \epsilon_0 = \int_{\tau'}^{\tau''} \epsilon_y(\tau) \sin[\omega_0(\tau''-\tau)] d\tau \int_{\tau'}^{\tau''} \epsilon_y(\theta) \sin[\omega_0(\theta-\tau')] d\theta, \quad (26)$$

$$\epsilon_{ab} = (\epsilon_a + \epsilon_b)/m \sin(\omega_0 T) \quad \text{and} \quad H = 1 - 2 \tan(\omega_0 T/2)/\omega_0 T.$$

Combining eq. (5) with eq. (23) we have the propagator eq. (4) as our final result. As a final remark we should mention that since $s(t) = s_x(t) = s_Y(t)$ and $\Omega(t) = \omega_x(t) = \omega_Y(t)$, we have in the continuum case

$$s^2(t)\omega(t) = \omega_0, \quad s^2(t)u(t) = 1 \quad \text{and} \quad \ddot{s}(t) + \Omega^2(t)s(t) = 0 \quad (27)$$

as we expect^{5,6}. Unfortunately, the present method can not be applied to the case of $\omega_x(t) \neq \omega_y(t)$, which will be studied in the near future.

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Resumo

Achando a transformação linear da coordenada dependente do tempo e a substituição do tempo, podemos calcular exatamente o propagador para uma partícula carregada, no campo eletromagnético dependente do tempo, e com um potencial quadrático também dependente do tempo.